# INFINITELY MANY SOLUTIONS FOR SOME NONLINEAR SUPERCRITICAL PROBLEMS WITH BREAK OF SYMMETRY 

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#### Abstract

In this paper, we prove the existence of infinitely many weak bounded solutions of the nonlinear elliptic problem $$
\begin{cases}-\operatorname{div}(a(x, u, \nabla u))+A_{t}(x, u, \nabla u)=g(x, u)+h(x) & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega\end{cases}
$$ where $\Omega \subset \mathbb{R}^{N}$ is an open bounded domain, $N \geq 3$, and $A(x, t, \xi), g(x, t), h(x)$ are given functions, with $A_{t}=\frac{\partial A}{\partial t}, a=\nabla_{\xi} A$, such that $A(x, \cdot \cdot \cdot)$ is even and $g(x, \cdot)$ is odd. To this aim, we use variational arguments and the Rabinowitz's perturbation method which is adapted to our setting and exploits a weak version of the Cerami-Palais-Smale condition. Furthermore, if $A(x, t, \xi)$ grows fast enough with respect to $t$, then the nonlinear term related to $g(x, t)$ may have also a supercritical growth.


Keywords: quasilinear elliptic equation, weak Cerami-Palais-Smale condition, Ambrosetti--Rabinowitz condition, break of symmetry, perturbation method, supercritical growth.

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## 1. INTRODUCTION

During the past years there has been a considerable amount of research in obtaining multiple critical points of functionals such as

$$
\mathcal{J}(u)=\int_{\Omega} A(x, u, \nabla u) d x-\int_{\Omega} F(x, u) d x, \quad u \in \mathcal{D}
$$

where $\mathcal{D}$ is a subset of a suitable Sobolev space, $A: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ and $F: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are given functions with $\Omega \subset \mathbb{R}^{N}$ open bounded domain, $N \geq 3$.

A family of model problems is given by

$$
A(x, t, \xi)=\sum_{i, j=1}^{N} a_{i, j}(x, t) \xi_{i} \xi_{j}
$$

with $\left(a_{i, j}(x, t)\right)_{i, j}$ elliptic matrix. In particular, if $a_{i, j}(x, t)=\frac{1}{2} \delta_{i}^{j} \bar{A}(x, t)$ for a given function $\bar{A}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, then it is $A(x, t, \xi)=\frac{1}{2} \bar{A}(x, t)|\xi|^{2}$.

In the simplest case $A(x, t, \xi)=\frac{1}{2}|\xi|^{2}$, functional $\mathcal{J}$, defined on $\mathcal{D}=H_{0}^{1}(\Omega)$, is the standard action functional associated to the classical semilinear elliptic problem

$$
\begin{cases}-\Delta u=f(x, u) & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega\end{cases}
$$

with $f(x, t)=\frac{\partial F}{\partial t}(x, t)$. If $F(x, t)$ has a subcritical growth with respect to $t$ and verifies other suitable assumptions, existence and multiplicity of critical points of the $C^{1}$ functional $\mathcal{J}$ have been widely studied by many authors in the last sixty years (see $[23,25]$ and references therein).

On the other hand, when $A(x, t, \xi)=\frac{1}{2} \bar{A}(x, t)|\xi|^{2}$, with $\bar{A}(x, t)$ smooth, bounded, far away from zero but $\bar{A}_{t}(x, t) \not \equiv 0$, even if $F(x, t) \equiv 0$, the corresponding functional

$$
\overline{\mathcal{J}}_{0}(u)=\frac{1}{2} \int_{\Omega} \bar{A}(x, u)|\nabla u|^{2} d x
$$

is defined in $H_{0}^{1}(\Omega)$ but is Gâteaux differentiable only along directions which are in $H_{0}^{1}(\Omega) \cap L^{\infty}(\Omega)$.

In the beginning, such a problem has been overcome by introducing suitable definitions of critical point and related existence results have been stated (see, e.g., $[2,3,17,21])$. More recently, it has been proved that suitable assumptions assure that functional $\mathcal{J}$ is $C^{1}$ in the Banach space $X=H_{0}^{1}(\Omega) \cap L^{\infty}(\Omega)$ equipped with the norm $\|\cdot\|_{X}$ given by the sum of the classical norms $\|\cdot\|_{H}$ on $H_{0}^{1}(\Omega)$ and $|\cdot|_{\infty}$ in $L^{\infty}(\Omega)$ (see [7] if $A(x, t, \xi)=\frac{1}{2} \bar{A}(x, t)|\xi|^{2}$ and [8] in the general case). Furthermore, its critical points in $X$ are weak bounded solutions of the quasilinear elliptic problem

$$
\begin{cases}-\operatorname{div}(a(x, u, \nabla u))+A_{t}(x, u, \nabla u)=f(x, u) & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega\end{cases}
$$

with

$$
\begin{equation*}
A_{t}(x, t, \xi)=\frac{\partial A}{\partial t}(x, t, \xi), a(x, t, \xi)=\left(\frac{\partial A}{\partial \xi_{1}}(x, t, \xi), \ldots, \frac{\partial A}{\partial \xi_{N}}(x, t, \xi)\right) . \tag{1.1}
\end{equation*}
$$

In order to study the set of critical points of a $C^{1}$ functional $J$ on a Banach space $\left(Y,\|\cdot\|_{Y}\right)$, but avoiding global compactness assumptions, Palais and Smale introduced the following condition (see [20]).
Definition 1.1. A functional $J$ satisfies the Palais-Smale condition at level $\beta(\beta \in \mathbb{R})$, briefly $(P S)_{\beta}$ condition, if any $(P S)_{\beta}$-sequence, i.e., any sequence $\left(u_{n}\right)_{n} \subset Y$ such that

$$
\lim _{n \rightarrow+\infty} J\left(u_{n}\right)=\beta \quad \text { and } \quad \lim _{n \rightarrow+\infty}\left\|d J\left(u_{n}\right)\right\|_{Y^{\prime}}=0
$$

converges in $Y$, up to subsequences.

We note that if $J$ satisfies $(P S)_{\beta}$ condition, the set of the critical points of $J$ at level $\beta$ is compact.

Later on, in [18] Cerami weakened such a definition by allowing a sequence to go to infinity but only if the gradient of the functional goes to zero "not too slowly".
Definition 1.2. A functional $J$ satisfies the Cerami's variant of Palais-Smale condition at level $\beta(\beta \in \mathbb{R})$, briefly $(C P S)_{\beta}$ condition, if any $(C P S)_{\beta}$-sequence, i.e., any sequence $\left(u_{n}\right)_{n} \subset Y$ such that

$$
\lim _{n \rightarrow+\infty} J\left(u_{n}\right)=\beta \quad \text { and } \quad \lim _{n \rightarrow+\infty}\left\|d J\left(u_{n}\right)\right\|_{Y^{\prime}}\left(1+\left\|u_{n}\right\|_{Y}\right)=0
$$

converges in $Y$, up to subsequences.
Unfortunately, our functional $\mathcal{J}$ in $X$ may have unbounded Palais-Smale sequences (see [11, Example 4.3]). Anyway, since $X$ is equipped with two different norms, namely $\|\cdot\|_{X}$ and $\|\cdot\|_{H}$, according to the ideas already developed in previous papers (see, e.g., $[7,9,11])$ a weaker version of $(C P S)$ condition can be introduced when the Banach space $Y$ is equipped with a second norm $\|\cdot\|_{*}$ such that $\left(Y,\|\cdot\|_{Y}\right)$ is continuously imbedded in $\left(Y,\|\cdot\|_{*}\right)$.
Definition 1.3. A functional $J$ satisfies a weak version of the Cerami's variant of Palais-Smale condition at level $\beta(\beta \in \mathbb{R})$, briefly $(w C P S)_{\beta}$ condition, if for every $(C P S)_{\beta}$-sequence $\left(u_{n}\right)_{n}$ a point $u \in Y$ exists such that
(i) $\lim _{n \rightarrow \infty}\left\|u_{n}-u\right\|_{*}=0 \quad$ (up to subsequences),
(ii) $J(u)=\beta, d J(u)=0$.

If $J$ satisfies the $(w C P S)_{\beta}$ condition at each level $\beta \in I, I$ real interval, we say that $J$ satisfies the $(w C P S)$ condition in $I$.

We note that if $\beta \in \mathbb{R}$ is such that $(w C P S)_{\beta}$ condition holds, then $\beta$ is a critical level if a $(C P S)_{\beta}$-sequence exists, furthermore the set of the critical points of $J$ at level $\beta$ is compact but with respect to the weaker norm $\|\cdot\|_{*}$.

Moreover, $(w C P S)_{\beta}$ condition is enough for proving a Deformation Lemma (see [9, Lemma 2.3]) and extending some critical point theorems (see [15]), but, contrary to the classical $(C P S)$ condition, it it is not sufficient for finding multiple critical points if they occur at the same critical level. We remark that such a problem is avoided by replacing $(C P S)_{\beta}$-sequences with $(P S)_{\beta}$-sequences in Definition 1.3 and then a more general Deformation Lemma can be stated (see [11, Proposition 2.4]).

If $F(x, t)$ grows as $|t|^{q}$ with $2<q<2^{*}$ and satisfies the Ambrosetti-Rabinowitz condition, then it is possible to find at least one critical point, or infinitely many ones if $\mathcal{J}$ is even, by applying a suitable version of the Mountain Pass Theorem, or its symmetric variant (see $[7,8]$ and, for the abstract setting, [9]). Such results still hold if $F(x, t)$ has a suitable supercritical growth but function $A(x, t, \xi)$ satisfies "good" growth assumptions (see [15] and, for a different type of supercritical problems, see, e.g., [1]).

Furthermore, the existence of multiple critical points has been stated in $[10,11,14]$ for different sets of hypotheses on $F(x, t)$.

We note that all the previous results still hold if $A(x, t, \xi)$ increases as $|\xi|^{p}$ for any $p>1$.

More recently, infinitely many critical points have been found in break of symmetry if $A(x, t, \xi)=\frac{1}{2} \bar{A}(x, t)|\xi|^{2}$ and $F(x, t)=G(x, t)+h(x) t$, with $\bar{A}(x, \cdot)$ and $G(x, \cdot)$ even (see [16]).

In order to give an idea of the difficulties which arise dealing with functional $\mathcal{J}$ in $X$, in this paper we extend the result in [16] to a more general term $A(x, t, \xi)$ which increases as $|\xi|^{2}$.

More precisely, we look for weak bounded solutions of the nonlinear elliptic problem

$$
\begin{cases}-\operatorname{div}(a(x, u, \nabla u))+A_{t}(x, u, \nabla u)=g(x, u)+h(x) & \text { in } \Omega  \tag{1.2}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\Omega \subset \mathbb{R}^{N}$ is an open bounded domain, $N \geq 3$, and $A: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$, $g: \Omega \times \mathbb{R} \rightarrow \mathbb{R}, h: \Omega \rightarrow \mathbb{R}$ are given functions, with $A(x, \cdot, \cdot)$ even and $g(x, \cdot)$ odd.

Hence, as already remarked, under suitable assumptions for $A(x, t, \xi), g(x, t)$ and $h(x)$, we study the existence of infinitely many critical points of the $C^{1}$ functional

$$
\begin{equation*}
\mathcal{J}(u)=\int_{\Omega} A(x, u, \nabla u) d x-\int_{\Omega} G(x, u) d x-\int_{\Omega} h u d x, \quad u \in X \tag{1.3}
\end{equation*}
$$

with $G(x, t)=\int_{0}^{t} g(x, s) d s$.
If $h(x) \equiv 0$, functional $\mathcal{J}$ in (1.3) reduces to the even map

$$
\begin{equation*}
\mathcal{J}_{0}(u)=\int_{\Omega} A(x, u, \nabla u) d x-\int_{\Omega} G(x, u) d x, \quad u \in X \tag{1.4}
\end{equation*}
$$

If $h(x) \not \equiv 0$ the symmetry is broken. Anyway, some perturbation methods, introduced in the classical case $A(x, t, \xi) \equiv \frac{1}{2}|\xi|^{2}$, allow one to prove the existence of infinitely many critical points also for a not-even functional (see [4, 5, 22, 24]). Here, we prove a multiplicity result for our functional $\mathcal{J}$ by adapting to our setting the Rabinowitz's perturbation method in [22].

As our main theorem needs a list of hypotheses, we will give its complete statement in Section 2 (see Theorem 2.6). Anyway, we point out that, as in [15, 16], if function $A(x, t, \xi)$ satisfies "good" growth assumptions then the nonlinear term $G(x, t)$ can have also a supercritical growth. Moreover, in the particular case $G(x, t)=\frac{1}{q}|t|^{q}$, the interval of variability for $q$ is larger than the one found by Tanaka in [26] (see Remark 2.9).

This paper is organized as follows. In Section 2, we introduce the hypotheses for $A(x, t, \xi), G(x, t)$ and $h(x)$, we give the variational formulation of our problem and state our main result. Then, in Section 3 we introduce the perturbation method and in Section 4 we prove that $\mathcal{J}$ satisfies a weak version of the Cerami-Palais-Smale condition. Finally, in Section 5, we give the proof of our main theorem.

## 2. VARIATIONAL SETTING AND THE MAIN RESULT

From now on, let $A: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ and $g: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be such that, using the notations in (1.1), the following conditions hold:
$\left(H_{0}\right) A(x, t, \xi)$ is a $C^{1}$ Carathéodory function, i.e.,
$A(\cdot, t, \xi): x \in \Omega \mapsto A(x, t, \xi) \in \mathbb{R}$ is measurable for all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$,
$A(x, \cdot, \cdot):(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N} \mapsto A(x, t, \xi) \in \mathbb{R}$ is $C^{1}$ for a.e. $x \in \Omega ;$
$\left(H_{1}\right)$ some positive continuous functions $\Phi_{i}, \phi_{i}: \mathbb{R} \rightarrow \mathbb{R}, i \in\{1,2\}$, exist such that

$$
\begin{aligned}
\left|A_{t}(x, t, \xi)\right| & \leq \Phi_{1}(t)+\phi_{1}(t)|\xi|^{2} \quad \text { a.e. in } \Omega, \text { for all }(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N} \\
|a(x, t, \xi)| & \leq \Phi_{2}(t)+\phi_{2}(t)|\xi| \quad \text { a.e. in } \Omega, \text { for all }(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}
\end{aligned}
$$

$\left(G_{0}\right) g \in C(\bar{\Omega} \times \mathbb{R}, \mathbb{R}) ;$
$\left(G_{1}\right) a_{1}, a_{2}>0$ and $q \geq 1$ exist such that

$$
|g(x, t)| \leq a_{1}+a_{2}|t|^{q-1} \quad \text { a.e. in } \Omega, \text { for all } t \in \mathbb{R} .
$$

Remark 2.1. From $\left(G_{1}\right)$ it follows that $a_{1}^{\prime}, a_{2}^{\prime}>0$ exist such that

$$
\begin{equation*}
|G(x, t)| \leq a_{1}^{\prime}+a_{2}^{\prime}|t|^{q} \quad \text { a.e in } \Omega \text {, for all } t \in \mathbb{R} \text {. } \tag{2.1}
\end{equation*}
$$

We note that, unlike assumption $\left(G_{1}\right)$ in [8], no upper bound on $q$ is actually required.
In order to investigate the existence of weak solutions of the nonlinear problem (1.2), we consider the Banach space $\left(X,\|\cdot\|_{X}\right)$ defined as

$$
X:=H_{0}^{1}(\Omega) \cap L^{\infty}(\Omega), \quad\|u\|_{X}=\|u\|_{H}+|u|_{\infty}
$$

(here and in the following, $|\cdot|$ will denote the standard norm on any Euclidean space as the dimension of the considered vector is clear and no ambiguity arises).

Moreover, from the Sobolev Imbedding Theorem, for any $r \in\left[1,2^{*}\left[, 2^{*}=\frac{2 N}{N-2}\right.\right.$ as $N \geq 3$, a constant $\sigma_{r}>0$ exists, such that

$$
\begin{equation*}
|u|_{r} \leq \sigma_{r}\|u\|_{H} \quad \text { for all } u \in H_{0}^{1}(\Omega) \tag{2.2}
\end{equation*}
$$

and the imbedding $H_{0}^{1}(\Omega) \hookrightarrow \hookrightarrow L^{r}(\Omega)$ is compact, where $\left(L^{r}(\Omega),|\cdot|_{r}\right)$ is the standard Lebesgue space.

From definition, $X \hookrightarrow H_{0}^{1}(\Omega)$ and $X \hookrightarrow L^{\infty}(\Omega)$ with continuous imbeddings, and thus $X \hookrightarrow L^{r}(\Omega)$ for any $r \geq 1$, too.

If the perturbation term $h: \Omega \rightarrow \mathbb{R}$ is such that the associated operator

$$
\mathcal{L}: u \in X \mapsto \int_{\Omega} h(x) u(x) d x \in \mathbb{R}
$$

belongs to $X^{\prime}$, then $\left(H_{0}\right)$ and $\left(G_{0}\right)$ allow us to consider the functional $\mathcal{J}: X \rightarrow \mathbb{R}$ defined as in (1.3) and the following regularity result holds.

Proposition 2.2. Let us assume that $\mathcal{L} \in X^{\prime}$, the functions $A(x, t, \xi)$ and $g(x, t)$ satisfy conditions $\left(H_{0}\right)-\left(H_{1}\right),\left(G_{0}\right)-\left(G_{1}\right)$ and two positive continuous functions $\Phi_{0}$, $\phi_{0}: \mathbb{R} \rightarrow \mathbb{R}$ exist such that

$$
\begin{equation*}
|A(x, t, \xi)| \leq \Phi_{0}(t)+\phi_{0}(t)|\xi|^{2} \quad \text { a.e. in } \Omega, \text { for all }(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N} \tag{2.3}
\end{equation*}
$$

If $\left(u_{n}\right)_{n} \subset X, u \in X$ are such that

$$
\left\|u_{n}-u\right\|_{H} \rightarrow 0, \quad u_{n} \rightarrow u \text { a.e. in } \Omega \quad \text { if } n \rightarrow+\infty
$$

$$
\text { and } M>0 \text { exists so that }\left|u_{n}\right|_{\infty} \leq M \text { for all } n \in \mathbb{N} \text {, }
$$

then

$$
\mathcal{J}\left(u_{n}\right) \rightarrow \mathcal{J}(u) \quad \text { and } \quad\left\|d \mathcal{J}\left(u_{n}\right)-d \mathcal{J}(u)\right\|_{X^{\prime}} \rightarrow 0 \quad \text { if } n \rightarrow+\infty,
$$

with

$$
\begin{align*}
\langle d \mathcal{J}(v), w\rangle= & \int_{\Omega}\left(a(x, v, \nabla v) \cdot \nabla w+A_{t}(x, v, \nabla v) w\right) d x \\
& -\int_{\Omega} g(x, v) w d x-\int_{\Omega} h w d x \quad \text { for any } v, w \in X . \tag{2.4}
\end{align*}
$$

Hence, $\mathcal{J}$ is a $C^{1}$ functional on $X$.
Proof. The proof follows by combining the arguments in [15, Proposition 3.2] with those ones in [16, Proposition 3.3].

In order to prove more properties of functional $\mathcal{J}$ in (1.3), we require that some constants $\alpha_{i}>0, i \in\{1,2,3\}, \eta_{j}>0, j \in\{1,2\}$, and $s \geq 0, \mu>2, R_{0} \geq 1$, exist such that the following hypotheses are satisfied:
$\left(H_{2}\right) A(x, t, \xi) \leq \eta_{1} a(x, t, \xi) \cdot \xi \quad$ a.e. in $\Omega$ if $|(t, \xi)| \geq R_{0} ;$
$\left(H_{3}\right)|A(x, t, \xi)| \leq \eta_{2} \quad$ a.e. in $\Omega$ if $|(t, \xi)| \leq R_{0}$;
$\left(H_{4}\right) a(x, t, \xi) \cdot \xi \geq \alpha_{1}\left(1+|t|^{2 s}\right)|\xi|^{2} \quad$ a.e. in $\Omega, \quad$ for all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$;
$\left(H_{5}\right) a(x, t, \xi) \cdot \xi+A_{t}(x, t, \xi) t \geq \alpha_{2} a(x, t, \xi) \cdot \xi \quad$ a.e. in $\Omega$ if $|(t, \xi)| \geq R_{0}$;
$\left(H_{6}\right) \mu A(x, t, \xi)-a(x, t, \xi) \cdot \xi-A_{t}(x, t, \xi) t \geq \alpha_{3} a(x, t, \xi) \cdot \xi \quad$ a.e. in $\Omega$ if $|(t, \xi)| \geq R_{0}$;
$\left(H_{7}\right)$ for all $\xi, \xi^{*} \in \mathbb{R}^{N}, \xi \neq \xi^{*}$, it is

$$
\left[a(x, t, \xi)-a\left(x, t, \xi^{*}\right)\right] \cdot\left[\xi-\xi^{*}\right]>0 \quad \text { a.e. in } \Omega, \text { for all } t \in \mathbb{R} ;
$$

$\left(G_{2}\right) g(x, t)$ satisfies the Ambrosetti-Rabinowitz condition, i.e.

$$
0<\mu G(x, t) \leq g(x, t) t \quad \text { for all } x \in \Omega \text { if }|t| \geq R_{0} .
$$

Remark 2.3. If $\left(H_{1}\right)-\left(H_{6}\right)$ hold, we deduce that in $\left(H_{5}\right)$ we can take $\alpha_{2} \leq 1$ and suitable constants $\eta_{3}, \eta_{4}>0$ exist such that for a.e. $x \in \Omega$, all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$ the following estimates are satisfied:

$$
\begin{align*}
A(x, t, \xi) & \geq \alpha_{1} \frac{\alpha_{2}+\alpha_{3}}{\mu}\left(1+|t|^{2 s}\right)|\xi|^{2}-\eta_{3}  \tag{2.5}\\
|A(x, t, \xi)| & \leq \eta_{1}\left(\Phi_{2}(t)+\phi_{2}(t)\right)|\xi|^{2}+\eta_{1} \Phi_{2}(t)+\eta_{2}  \tag{2.6}\\
a(x, t, \xi) \cdot \xi & \leq \frac{\eta_{4} \mu}{\alpha_{2}+\alpha_{3}}|t|^{\mu-\frac{1+\alpha_{3}}{\eta_{1}}}|\xi|^{2} \quad \text { if }|t| \geq 1 \text { and }|\xi| \geq R_{0} \tag{2.7}
\end{align*}
$$

(for more details, see Remarks 3.3, 3.4 and 3.5 in [15]).

Thus, from (2.6) the growth condition (2.3) holds and Proposition 2.2 applies. At last, we note that $\left(H_{4}\right)$ and (2.7) imply that

$$
\begin{equation*}
0 \leq 2 s \leq \mu-\frac{1+\alpha_{3}}{\eta_{1}} \tag{2.8}
\end{equation*}
$$

and, in particular,

$$
\begin{equation*}
\mu>\frac{\alpha_{3}}{\eta_{1}} \tag{2.9}
\end{equation*}
$$

From $\mu>2$ and (2.8) it follows that $\max \{2,2 s\}<\mu$. Actually, a stronger inequality on $\mu$ can be deduced from a careful estimate of $A(x, t, \xi)$.
Remark 2.4. If $\left(H_{1}\right)-\left(H_{6}\right)$ hold, some constants $\alpha_{1}^{*}, \alpha_{2}^{*}>0$ exist such that

$$
\begin{equation*}
|A(x, t, \xi)| \leq \alpha_{1}^{*}\left(1+|t|^{\mu-\frac{\alpha_{3}}{\eta_{1}}}\right)+\alpha_{2}^{*}\left(1+|t|^{\mu-\frac{\alpha_{3}}{\eta_{1}}-2}\right)|\xi|^{2} \tag{2.10}
\end{equation*}
$$

for a.e. $x \in \Omega$, all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$ (for more details, see [8, Lemma 6.5]).
Therefore, from (2.5) and (2.10) it results

$$
2(s+1) \leq \mu-\frac{\alpha_{3}}{\eta_{1}}
$$

Then, since we can always choose $\eta_{1}$ in $\left(H_{2}\right)$ large enough, it follows that

$$
\begin{equation*}
0 \leq 2(s+1)<\mu \tag{2.11}
\end{equation*}
$$

Remark 2.5. Assumptions $\left(G_{0}\right)-\left(G_{2}\right)$ and direct computations imply that some strictly positive constants $a_{3}, a_{4}$ and $a_{5}$ exist such that

$$
\begin{equation*}
\frac{1}{\mu}\left(g(x, t) t+a_{3}\right) \geq G(x, t)+a_{4} \geq a_{5}|t|^{\mu} \quad \text { for all }(x, t) \in \Omega \times \mathbb{R} \tag{2.12}
\end{equation*}
$$

Hence, in our setting of assumptions on $A(x, t, \xi)$ and $g(x, t)$, estimates (2.1), (2.11) and (2.12) imply that

$$
\begin{equation*}
2(s+1)<\mu \leq q . \tag{2.13}
\end{equation*}
$$

Now, we are able to state our main result.
Theorem 2.6. Assume that $A(x, t, \xi), g(x, t)$ and $h(x)$ satisfy conditions $\left(H_{0}\right)-\left(H_{7}\right)$, $\left(G_{0}\right)-\left(G_{2}\right)$ and
$\left(H_{8}\right) A(x,-t,-\xi)=A(x, t, \xi) \quad$ for a.e. $x \in \Omega$, for all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$;
$\left(G_{3}\right) g(x,-t)=-g(x, t) \quad$ for all $(x, t) \in \Omega \times \mathbb{R}$;
$\left(h_{0}\right) h \in L^{\nu}(\Omega) \cap L^{\mu^{\prime}}(\Omega)$ with $\nu>\frac{N}{2}$ and $\mu^{\prime}=\frac{\mu}{\mu-1}$.
If

$$
\begin{equation*}
q<2^{*}(s+1) \quad \text { and } \quad \frac{\mu}{\mu-1}<\frac{2 q}{N(q-2-2 s)} \tag{2.14}
\end{equation*}
$$

with $s$ as in $\left(H_{4}\right), q$ as in $\left(G_{1}\right)$ and $\mu$ as in $\left(G_{2}\right)$ and $\left(H_{6}\right)$, then functional $\mathcal{J}$ has infinitely many critical points $\left(u_{n}\right)_{n}$ in $X$ such that $\mathcal{J}\left(u_{n}\right) ~ \nearrow+\infty$; hence, problem (1.2) has infinitely many weak (bounded) solutions.

Remark 2.7. We note that $h \in L^{\mu^{\prime}}(\Omega)$ implies $\mathcal{L} \in X^{\prime}$ and, from $X \hookrightarrow L^{\mu}(\Omega)$ and Hölder inequality, we obtain the estimate

$$
\begin{equation*}
\left|\int_{\Omega} h u d x\right| \leq|h|_{\mu^{\prime}}|u|_{\mu} \quad \text { for all } u \in X . \tag{2.15}
\end{equation*}
$$

On the other hand, we need $h \in L^{\nu}(\Omega)$ only for proving the boundedness of the weak limit of the $(C P S)$-sequences in $H_{0}^{1}(\Omega)$ (see the proof of Proposition 4.5). Anyway, if $N \geq 4$ it results $L^{\nu}(\Omega) \cap L^{\mu^{\prime}}(\Omega)=L^{\nu}(\Omega)$ as $\mu>2$ implies $\mu^{\prime}<\frac{N}{2}$.

Remark 2.8. For the classical problem (1.2) with $A(x, t, \xi) \equiv \frac{1}{2}|\xi|^{2}$, it is $s=0$, hence Theorem 2.6 reduces to the well known result stated in [26] (see also [12,13] where a similar result is stated for a problem with non-homogeneous boundary conditions).

Furthermore, in the quasilinear model case $A(x, t, \xi)=\frac{1}{2} \bar{A}(x, t)|\xi|^{2}$, conditions $\left(H_{2}\right)$ and $\left(H_{7}\right)$ are trivially verified and Theorem 2.6 reduces to [16, Theorem 3.4].

Remark 2.9. In the particular case $g(x, t)=|t|^{q-2} t$ we have $\mu=q$, then estimate (2.11) and condition (2.14) imply

$$
2(s+1)<q<\frac{2(N-1)}{N-2}+\frac{2 N s}{N-2} .
$$

We recall that, if $A(x, t, \xi) \equiv \frac{1}{2}|\xi|^{2}$, in [26] Tanaka proves the existence of infinitely many solutions if

$$
\begin{equation*}
2<q<\frac{2(N-1)}{N-2} \tag{2.16}
\end{equation*}
$$

Therefore, if $s>0$ the length of the allowed range of $q$, equal to $\frac{2}{N-2}+\frac{4 s}{N-2}$, is larger than $\frac{2}{N-2}$ which comes from (2.16).

## 3. A PERTURBATION METHOD

From now on, assume that $\left(H_{1}\right)-\left(H_{6}\right),\left(G_{0}\right)-\left(G_{2}\right)$ and $\left(h_{0}\right)$ hold. Thus, from Proposition 2.2 and Remarks 2.3 and 2.7, $\mathcal{J}$ in (1.3) is a $C^{1}$ functional on $X$.

By $\mathcal{J}_{0}$ we denote the functional $\mathcal{J}$ corresponding to $h \equiv 0$ defined as in (1.4).
We note that, if $\left(H_{8}\right)$ and $\left(G_{3}\right)$ hold, then $\mathcal{J}_{0}$ is the even symmetrization of $\mathcal{J}$, as

$$
\frac{1}{2}(\mathcal{J}(u)+\mathcal{J}(-u))=\mathcal{J}_{0}(u) \quad \text { for all } u \in X
$$

We know that, under the additional assumptions $\left(H_{7}\right)-\left(H_{8}\right)$ and $\left(G_{3}\right)$, the existence of infinitely many critical points for $\mathcal{J}_{0}$ in $X$ has been proved in [15]. Here, we prove a multiplicity result for the complete functional $\mathcal{J}$ in spite of the loss of symmetry. To this aim, we use a suitable version of the Rabinowitz's perturbation method in [22] (see also [16, Section 4]) which requires the following technical lemmas.

Lemma 3.1. For all $u \in X$ it results

$$
\begin{aligned}
\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)-\langle d \mathcal{J}(u), u\rangle \geq & \frac{\alpha_{3}}{\mu \eta_{1}} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x \\
& -\left(\mu-\frac{\alpha_{3}}{\eta_{1}}-1\right) \int_{\Omega} h u d x-a_{6}
\end{aligned}
$$

with $\eta_{1}$ as in $\left(H_{2}\right), \mu$ and $\alpha_{3}$ as in $\left(H_{6}\right), a_{3}$ as in (2.12) and $a_{6}>0$ a suitable constant. Proof. Taking $u \in X$, from (1.3), (2.4) and direct computations we have that

$$
\begin{aligned}
& \left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)-\langle d \mathcal{J}(u), u\rangle \\
& =\int_{\Omega}\left(\mu A(x, u, \nabla u)-a(x, u, \nabla u) \cdot \nabla u-A_{t}(x, u, \nabla u) u\right) d x \\
& \quad-\frac{\alpha_{3}}{\eta_{1}} \int_{\Omega} A(x, u, \nabla u) d x-\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \int_{\Omega}\left(G(x, u)+a_{4}\right) d x \\
& \quad+a_{4}\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right)|\Omega|+\int_{\Omega}\left(g(x, u) u+a_{3}\right) d x-a_{3}|\Omega|-\left(\mu-\frac{\alpha_{3}}{\eta_{1}}-1\right) \int_{\Omega} h u d x .
\end{aligned}
$$

Then, setting

$$
\Omega_{R_{0}}^{u}=\left\{x \in \Omega:|(u(x), \nabla u(x))| \geq R_{0}\right\}
$$

from $\left(H_{1}\right),\left(H_{6}\right),(2.6),(2.9)$ and (2.12) a constant $a_{6}>0$ exists such that

$$
\begin{aligned}
\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)-\langle d \mathcal{J}(u), u\rangle \geq & \alpha_{3} \int_{\Omega_{R_{0}}^{u}} a(x, u, \nabla u) \cdot \nabla u d x \\
& -\frac{\alpha_{3}}{\eta_{1}} \int_{\Omega_{R_{0}}^{u}} A(x, u, \nabla u) d x+\frac{\alpha_{3}}{\eta_{1} \mu} \int_{\Omega}\left(g(x, u)+a_{3}\right) d x \\
& -\left(\mu-\frac{\alpha_{3}}{\eta_{1}}-1\right) \int_{\Omega} h u d x-a_{6}
\end{aligned}
$$

hence, the thesis follows from $\left(H_{2}\right)$.
Lemma 3.2. A constant $\alpha^{*}=\alpha^{*}\left(|h|_{\mu^{\prime}}\right)>0$ exists, such that

$$
u \in X,|\langle d \mathcal{J}(u), u\rangle| \leq 1 \quad \Longrightarrow \quad \frac{1}{\mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x \leq \alpha^{*}\left(\mathcal{J}^{2}(u)+1\right)^{\frac{1}{2}}
$$

with $\mu$ as in $\left(H_{6}\right)$ and $a_{3}$ as in (2.12).

Proof. From Lemma 3.1, (2.9) and (2.15) it follows that

$$
\begin{align*}
\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)-\langle d \mathcal{J}(u), u\rangle \geq & \frac{\alpha_{3}}{\eta_{1} \mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x  \tag{3.1}\\
& -\left(\mu-\frac{\alpha_{3}}{\eta_{1}}+1\right)|h|_{\mu^{\prime}}|u|_{\mu}-a_{6}
\end{align*}
$$

(as useful in the following, we make the constant $\mu-\frac{\alpha_{3}}{\eta_{1}}-1$ grow to $\mu-\frac{\alpha_{3}}{\eta_{1}}+1$ ).
Now, from one hand, (3.1), Young inequality with $\varepsilon=\frac{\alpha_{3}}{2 \eta_{1}} a_{5}$, and (2.12) imply the existence of a suitable constant $b_{0}=b_{0}\left(\alpha_{3}, \eta_{1}, \mu, a_{5}\right)>0$ such that for all $u \in X$ we have

$$
\begin{align*}
& \frac{\alpha_{3}}{\eta_{1} \mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x-\left(\mu-\frac{\alpha_{3}}{\eta_{1}}+1\right)|h|_{\mu^{\prime}}|u|_{\mu}-a_{6} \\
& \geq \frac{\alpha_{3}}{\eta_{1} \mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x-\frac{\alpha_{3}}{2 \eta_{1}} a_{5}|u|_{\mu}^{\mu}  \tag{3.2}\\
& \quad-b_{0}\left(\mu-\frac{\alpha_{3}}{\eta_{1}}+1\right)^{\mu^{\prime}}|h|_{\mu^{\prime}}^{\mu^{\prime}}-a_{6} \\
& \geq \frac{\alpha_{3}}{2 \eta_{1} \mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x-a_{7}
\end{align*}
$$

with $a_{7}=b_{0}\left(\mu-\frac{\alpha_{3}}{\eta_{1}}+1\right)^{\mu^{\prime}}|h|_{\mu^{\prime}}^{\mu^{\prime}}+a_{6}$.
On the other hand, taking $u \in X$ such that $|\langle d \mathcal{J}(u), u\rangle| \leq 1$, we have

$$
\begin{equation*}
\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)-\langle d \mathcal{J}(u), u\rangle \leq\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)+1 \tag{3.3}
\end{equation*}
$$

Whence, (3.1)-(3.3) imply

$$
\left(\mu-\frac{\alpha_{3}}{\eta_{1}}\right) \mathcal{J}(u)+1 \geq \frac{\alpha_{3}}{2 \eta_{1} \mu} \int_{\Omega}\left(g(x, u) u+a_{3}\right) d x-a_{7}
$$

and the conclusion follows with $\alpha^{*}=2 \sqrt{2} \frac{\eta_{1}}{\alpha_{3}} \max \left\{\mu-\frac{\alpha_{3}}{\eta_{1}}, 1+a_{7}\right\}$.
Now, modifying functional $\mathcal{J}$, we introduce the new map

$$
\begin{equation*}
\mathcal{J}_{1}(u)=\int_{\Omega} A(x, u, \nabla u) d x-\int_{\Omega} G(x, u) d x-\psi(u) \int_{\Omega} h u d x, \quad u \in X \tag{3.4}
\end{equation*}
$$

where

$$
\begin{equation*}
\psi(u)=\chi\left(\frac{1}{\mathcal{F}(u)} \int_{\Omega}\left(G(x, u)+a_{4}\right) d x\right), \quad \mathcal{F}(u)=2 \alpha^{*}\left(\mathcal{J}^{2}(u)+1\right)^{\frac{1}{2}} \tag{3.5}
\end{equation*}
$$

with $\alpha^{*}$ as in Lemma 3.2, and $\chi \in C^{\infty}(\mathbb{R},[0,1])$ is a decreasing cut-function such that

$$
\chi(t)= \begin{cases}1 & \text { if } t \leq 1  \tag{3.6}\\ 0 & \text { if } t \geq 2\end{cases}
$$

and $-2<\chi^{\prime}(t)<0$ for all $\left.t \in\right] 1,2[$.
Clearly, it is

$$
\mathcal{J}_{1}(u)=\mathcal{J}(u)-(\psi(u)-1) \int_{\Omega} h u d x, \quad u \in X
$$

where we have

$$
\begin{equation*}
0 \leq \psi(u) \leq 1 \quad \text { for all } u \in X \tag{3.7}
\end{equation*}
$$

Also if the symmetric conditions $\left(H_{8}\right)$ and $\left(G_{3}\right)$ hold, functional $\mathcal{J}_{1}$ is not even. Anyway, we can control its loss of symmetry.

Lemma 3.3. Under the further hypotheses $\left(H_{8}\right)$ and $\left(G_{3}\right)$, a constant $k_{0}=k_{0}\left(|h|_{\mu^{\prime}}\right)>0$ exists, such that

$$
\left|\mathcal{J}_{1}(u)-\mathcal{J}_{1}(-u)\right| \leq k_{0}\left(\left|\mathcal{J}_{1}(u)\right|^{\frac{1}{\mu}}+1\right) \quad \text { for all } u \in X
$$

Proof. For the proof, see [16, Lemma 4.4].
From Proposition 2.2, direct computations imply that $\mathcal{J}_{1}$ is a $C^{1}$ functional on $X$ and for all $u \in X$ we have

$$
\begin{aligned}
\left\langle d \mathcal{J}_{1}(u), u\right\rangle= & \left(1+T_{1}(u)\right)\langle d \mathcal{J}(u), u\rangle-\left(T_{2}(u)-T_{1}(u)\right) \int_{\Omega} g(x, u) u d x \\
& -(\psi(u)-1) \int_{\Omega} h u d x
\end{aligned}
$$

with

$$
\begin{aligned}
& T_{1}(u)=\chi^{\prime}\left(\frac{1}{\mathcal{F}(u)} \int_{\Omega}\left(G(x, u)+a_{4}\right) d x\right) \frac{\left(2 \alpha^{*}\right)^{2} \mathcal{J}(u)}{\mathcal{F}^{3}(u)} \int_{\Omega}\left(G(x, u)+a_{4}\right) d x \int_{\Omega} h u d x \\
& T_{2}(u)=T_{1}(u)+\chi^{\prime}\left(\frac{1}{\mathcal{F}(u)} \int_{\Omega}\left(G(x, u)+a_{4}\right) d x\right) \frac{1}{\mathcal{F}(u)} \int_{\Omega} h u d x .
\end{aligned}
$$

Lemma 3.4. Functional $\mathcal{J}_{1}$ verifies the following conditions:
(i) two strictly positive constants $M_{0}=M_{0}\left(|h|_{\mu^{\prime}}\right)$ and $a_{0}=a_{0}\left(|h|_{\mu^{\prime}}\right)$ exist, such that for all $M \geq M_{0}$ we have

$$
u \in \operatorname{supp} \psi, \quad \mathcal{J}_{1}(u) \geq M \quad \Longrightarrow \quad \mathcal{J}(u) \geq a_{0} M
$$

(ii) for any $\varepsilon>0$ a constant $M_{\varepsilon}>0$ exists, such that

$$
u \in X, \quad \mathcal{J}_{1}(u) \geq M_{\varepsilon} \quad \Longrightarrow \quad\left|T_{1}(u)\right| \leq \varepsilon, \quad\left|T_{2}(u)\right| \leq \varepsilon
$$

(iii) a constant $M_{1}>0$ exists such that $u \in X$,

$$
\mathcal{J}_{1}(u) \geq M_{1},\left|\left\langle d \mathcal{J}_{1}(u), u\right\rangle\right| \leq \frac{1}{2} \quad \Longrightarrow \quad \mathcal{J}_{1}(u)=\mathcal{J}(u), d \mathcal{J}_{1}(u)=d \mathcal{J}(u)
$$

Proof. For the proof, see Lemmas 4.3, 4.5 and 4.7 in [16].
Remark 3.5. Any critical point of $\mathcal{J}$ is also a critical point of $\mathcal{J}_{1}$ with the same critical level. In fact, if $u$ is critical point of $\mathcal{J}$ in $X$, from (2.12), Lemma 3.2 and (3.5) it follows that

$$
\int_{\Omega}\left(G(x, u)+a_{4}\right) d x \leq \frac{1}{2} \mathcal{F}(u)
$$

hence, definition (3.6) implies that $\psi(u)=1, \psi^{\prime}(u)=0$, and then

$$
\mathcal{J}_{1}(u)=\mathcal{J}(u), \quad d \mathcal{J}_{1}(u)=0
$$

On the other hand, (iii) of Lemma 3.4 states that also the vice versa is true but only for large enough critical levels.

## 4. THE WEAK CERAMI-PALAIS-SMALE CONDITION

The aim of this section is proving that our perturbed functional $\mathcal{J}_{1}$ satisfies $(w C P S)_{\beta}$ condition (see Definition 1.3) but if $\beta$ is large enough.

From now on, let $\mathbb{N}=\{1,2, \ldots\}$ and we denote by $|C|$ the usual Lebesgue measure of a measurable set $C$ in $\mathbb{R}^{N}$.

Firstly, we recall the following result.
Proposition 4.1. If $q<2^{*}(s+1)$, then functional $\mathcal{J}_{0}$ satisfies the $(w C P S)$ condition in $\mathbb{R}$.

Proof. For the proof, see [15, Proposition 3.10].
Our next step is proving that also $\mathcal{J}$ satisfies $(w C P S)$ condition in $\mathbb{R}$ for any $q<2^{*}(s+1)$ even if we have $h \not \equiv 0$. To this aim, we need the following variants of imbedding theorems.

Lemma 4.2. Fix $s \geq 0$ and let $\left(u_{n}\right)_{n} \subset X$ be a sequence such that

$$
\begin{equation*}
\left(\int_{\Omega}\left(1+\left|u_{n}\right|^{2 s}\right)\left|\nabla u_{n}\right|^{2} d x\right)_{n} \quad \text { is bounded. } \tag{4.1}
\end{equation*}
$$

Then, $u \in H_{0}^{1}(\Omega)$ exists such that $|u|^{s} u \in H_{0}^{1}(\Omega)$, too, and, up to subsequences, if $n \rightarrow+\infty$ we have

$$
\begin{align*}
& u_{n} \rightharpoonup u \text { weakly in } H_{0}^{1}(\Omega),  \tag{4.2}\\
& \left|u_{n}\right|^{s} u_{n} \rightharpoonup|u|^{s} u \text { weakly in } H_{0}^{1}(\Omega),  \tag{4.3}\\
& u_{n} \rightarrow u \text { a.e. in } \Omega,  \tag{4.4}\\
& u_{n} \rightarrow u \text { strongly in } L^{r}(\Omega) \text { for each } r \in\left[1,2^{*}(s+1)[.\right. \tag{4.5}
\end{align*}
$$

Proof. For the proof, see [15, Lemma 3.8].
Lemma 4.3. If $q<2^{*}(s+1)$, then a constant $c_{s}>0$ exists such that

$$
|u|_{\mu} \leq c_{s}\left(\int_{\Omega}\left(1+|u|^{2 s}\right)|\nabla u|^{2} d x\right)^{\frac{1}{2(s+1)}} \quad \text { for all } u \in X
$$

Proof. Taking $u \in X$, we note that

$$
\begin{equation*}
\left|\nabla\left(|u|^{s} u\right)\right|^{2}=(s+1)^{2}|u|^{2 s}|\nabla u|^{2} \quad \text { a.e. in } \Omega \text {. } \tag{4.6}
\end{equation*}
$$

On the other hand, setting $q_{s}=\frac{q}{s+1}$, condition $q<2^{*}(s+1)$ implies $q_{s}<2^{*}$, then from (2.2) and (4.6) we have that

$$
\begin{aligned}
|u|_{q} & =\|\left.\left. u\right|^{s} u\right|_{q_{s}} ^{\frac{1}{s+1}} \leq\left(\sigma_{q_{s}}\left|\nabla\left(|u|^{s} u\right)\right|_{2}\right)^{\frac{1}{s+1}} \\
& \leq \sigma_{q_{s}}^{\frac{1}{s+1}}(s+1)^{\frac{1}{s+1}}\left(\int_{\Omega}\left(1+|u|^{2 s}\right)|\nabla u|^{2} d x\right)^{\frac{1}{2(s+1)}} .
\end{aligned}
$$

Hence, the thesis follows from (2.13).
Moreover, in order to prove the boundedness of the weak limit of a $(C P S)$-sequence, we need also the following particular version of [19, Theorem II.5.1].

Theorem 4.4. Taking $v \in H_{0}^{1}(\Omega)$, assume that $L_{0}>0$ and $k_{0} \in \mathbb{N}$ exist such that for all $\tilde{k} \geq k_{0}$ it is

$$
\int_{\Omega_{\bar{k}}^{+}}|\nabla v|^{2} d x \leq L_{0}\left(\int_{\Omega_{\bar{k}}^{+}}(v-\tilde{k})^{l} d x\right)^{\frac{2}{l}}+L_{0} \sum_{i=1}^{m} \tilde{k}^{l_{i}}\left|\Omega_{\tilde{k}}^{+}\right|^{1-\frac{2}{N}+\epsilon_{i}}
$$

with $\Omega_{\tilde{k}}^{+}=\{x \in \Omega: v(x)>\tilde{k}\}$, where $l, m, l_{i}, \epsilon_{i}$ are positive constants such that

$$
1 \leq l<2^{*}, \quad \epsilon_{i}>0, \quad 2 \leq l_{i}<\epsilon_{i} 2^{*}+2
$$

Then ess $\sup v$ is bounded from above by a positive constant which depends only on $N$, $|\Omega|, L_{0}, \stackrel{\Omega}{k}, l, m, \epsilon_{i}, l_{i},|u|_{2^{*}}$.

Proposition 4.5. If $q<2^{*}(s+1)$ then functional $\mathcal{J}$ satisfies the (wCPS) condition in $\mathbb{R}$.
Proof. Let $\beta \in \mathbb{R}$ be fixed and consider a $(C P S)_{\beta}$-sequence $\left(u_{n}\right)_{n} \subset X$, i.e.,

$$
\begin{equation*}
\mathcal{J}\left(u_{n}\right) \rightarrow \beta \quad \text { and } \quad\left\|d \mathcal{J}\left(u_{n}\right)\right\|_{X^{\prime}}\left(1+\left\|u_{n}\right\|_{X}\right) \rightarrow 0 \tag{4.7}
\end{equation*}
$$

For simplicity, here and in the following we will use the notation $\left(\varepsilon_{n}\right)_{n}$ for any infinitesimal sequence depending only on $\left(u_{n}\right)_{n}$.

From $\left(H_{1}\right),\left(H_{6}\right),(2.6),\left(G_{0}\right),\left(G_{2}\right),(2.15)$, direct computations, $\left(H_{4}\right)$ and Lemma 4.3, we have that some constants $a_{8}, a_{9}>0$ exist such that

$$
\begin{aligned}
\mu \beta+\varepsilon_{n} & =\mu \mathcal{J}\left(u_{n}\right)-\left\langle d \mathcal{J}\left(u_{n}\right), u_{n}\right\rangle \\
& \geq \alpha_{3} \int_{\Omega} a\left(x, u_{n}, \nabla u_{n}\right) \cdot \nabla u_{n} d x-a_{8}-(\mu-1)|h|_{\mu^{\prime}}\left|u_{n}\right|_{\mu} \\
& \geq \alpha_{1} \alpha_{3} \int_{\Omega}\left(1+\left|u_{n}\right|^{2 s}\right)\left|\nabla u_{n}\right|^{2} d x-a_{8}-a_{9}\left(\int_{\Omega}\left(1+\left|u_{n}\right|^{2 s}\right)\left|\nabla u_{n}\right|^{2} d x\right)^{\frac{1}{2(s+1)}}
\end{aligned}
$$

which implies (4.1). Then, from Lemma 4.2 it follows that $u \in H_{0}^{1}(\Omega)$ exists such that $|u|^{s} u \in H_{0}^{1}(\Omega)$, too, and, up to subsequences, (4.2)-(4.5) hold.

Now, we want to prove that $u$ is essentially bounded from above. Arguing by contradiction, let us assume that

$$
\begin{equation*}
\underset{\Omega}{\operatorname{ess} \sup ^{2}} u=+\infty ; \tag{4.8}
\end{equation*}
$$

thus, taking any $k \in \mathbb{N}, k>R_{0}\left(R_{0} \geq 1\right.$ as in the hypotheses), we have that

$$
\begin{equation*}
\left|\Omega_{k}^{+}\right|>0 \quad \text { with } \quad \Omega_{k}^{+}=\{x \in \Omega: u(x)>k\} \tag{4.9}
\end{equation*}
$$

Taking any $\tilde{k}>0$, we define the new function $R_{\tilde{k}}^{+}: t \in \mathbb{R} \rightarrow R_{\tilde{k}}^{+} t \in \mathbb{R}$ as

$$
R_{\tilde{k}}^{+} t= \begin{cases}0 & \text { if } t \leq \tilde{k} \\ t-\tilde{k} & \text { if } t>\tilde{k}\end{cases}
$$

Then, if $\tilde{k}=k^{s+1}$, from (4.3) it follows that

$$
R_{k^{s+1}}^{+}\left(\left|u_{n}\right|^{s} u_{n}\right) \rightharpoonup R_{k^{s+1}}^{+}\left(|u|^{s} u\right) \quad \text { weakly in } H_{0}^{1}(\Omega)
$$

thus, the sequentially weakly lower semicontinuity of $\|\cdot\|_{H}$ implies

$$
\begin{equation*}
\int_{\Omega_{k}^{+}}\left|\nabla\left(u^{s+1}\right)\right|^{2} d x \leq \liminf _{n \rightarrow+\infty} \int_{\Omega_{n, k}^{+}}\left|\nabla\left(u_{n}^{s+1}\right)\right|^{2} d x \tag{4.10}
\end{equation*}
$$

with $\Omega_{n, k}^{+}=\left\{x \in \Omega: u_{n}(x)>k\right\}$, as $|t|^{s} t>k^{s+1}$ if and only if $t>k$.

On the other hand, from $\left\|R_{k}^{+} u_{n}\right\|_{X} \leq\left\|u_{n}\right\|_{X}$, (4.7) and (4.9) it follows that $n_{k} \in \mathbb{N}$ exists so that

$$
\begin{equation*}
\left\langle d \mathcal{J}\left(u_{n}\right), R_{k}^{+} u_{n}\right\rangle<\left|\Omega_{k}^{+}\right| \quad \text { for all } n \geq n_{k} . \tag{4.11}
\end{equation*}
$$

Then, from $\left(H_{5}\right)$ (with $\left.\alpha_{2} \leq 1\right),\left(H_{4}\right),(4.6)$ and direct computations we have that

$$
\begin{aligned}
\left\langle d \mathcal{J}\left(u_{n}\right), R_{k}^{+} u_{n}\right\rangle \geq & \alpha_{2} \int_{\Omega_{n, k}^{+}} a\left(x, u_{n}, \nabla u_{n}\right) \cdot \nabla u_{n} d x-\int_{\Omega} g\left(x, u_{n}\right) R_{k}^{+} u_{n} d x \\
& -\int_{\Omega} h R_{k}^{+} u_{n} d x \\
\geq & \frac{\alpha_{1} \alpha_{2}}{(s+1)^{2}} \int_{\Omega_{n, k}^{+}}\left|\nabla\left(u_{n}^{s+1}\right)\right|^{2} d x-\int_{\Omega} g\left(x, u_{n}\right) R_{k}^{+} u_{n} d x-\int_{\Omega} h R_{k}^{+} u_{n} d x .
\end{aligned}
$$

Thus, from (4.11), it follows that

$$
\int_{\Omega_{n, k}^{+}}\left|\nabla\left(u_{n}^{s+1}\right)\right|^{2} d x \leq \frac{(s+1)^{2}}{\alpha_{1} \alpha_{2}}\left(\left|\Omega_{k}^{+}\right|+\int_{\Omega} g\left(x, u_{n}\right) R_{k}^{+} u_{n} d x+\int_{\Omega} h R_{k}^{+} u_{n} d x\right)
$$

where, since $q<2^{*}(s+1)$, from $\left(G_{1}\right)$ and (4.5) it results

$$
\int_{\Omega} g\left(x, u_{n}\right) R_{k}^{+} u_{n} d x \rightarrow \int_{\Omega} g(x, u) R_{k}^{+} u d x, \quad \int_{\Omega} h R_{k}^{+} u_{n} d x \rightarrow \int_{\Omega} h R_{k}^{+} u d x
$$

Hence, passing to the limit, (4.10) implies

$$
\int_{\Omega_{k}^{+}}\left|\nabla\left(u^{s+1}\right)\right|^{2} d x \leq \frac{(s+1)^{2}}{\alpha_{1} \alpha_{2}}\left(\left|\Omega_{k}^{+}\right|+\int_{\Omega} g(x, u) R_{k}^{+} u d x+\int_{\Omega} h R_{k}^{+} u d x\right) .
$$

Now, as $h \in L^{\nu}(\Omega)$ with $\nu>\frac{N}{2}$, by reasoning as in the last part of Step 2 in the proof of [16, Proposition 4.11], we are able to apply Theorem 4.4, then ess sup $u<+\infty$ in contradiction with (4.8).

Similar arguments prove also that $u$ is essentially bounded from below; hence, $u \in L^{\infty}(\Omega)$.

Taking $k \geq \max \left\{|u|_{\infty}, R_{0}\right\}+1\left(R_{0} \geq 1\right.$ as in the set of hypotheses $)$ and the truncation function $T_{k}: \mathbb{R} \rightarrow \mathbb{R}$ defined as

$$
T_{k} t= \begin{cases}t & \text { if }|t| \leq k, \\ k \frac{t}{|t|} & \text { if }|t|>k,\end{cases}
$$

thanks to the linearity of the term $v \mapsto \int_{\Omega} h v d x$ we can reason as in Steps 3 and 4 of the proof of [7, Proposition 3.4] and can prove that $\left(T_{k} u_{n}\right)_{n}$ is a Palais-Smale
sequence at level $\beta$, i.e. $\mathcal{J}\left(T_{k} u_{n}\right) \rightarrow \beta$ and $\left\|d \mathcal{J}\left(T_{k} u_{n}\right)\right\|_{X^{\prime}} \rightarrow 0$, and $\left\|T_{k} u_{n}-u\right\|_{H} \rightarrow 0$. Hence, also $\left\|u_{n}-u\right\|_{H} \rightarrow 0$ and, since $\left|T_{k} u_{n}\right|_{\infty} \leq k$ for all $n \in \mathbb{N}$, by applying Proposition 2.2 we have $\mathcal{J}(u)=\beta$ and $d \mathcal{J}(u)=0$.
Proposition 4.6. Let $q<2^{*}(s+1)$. Then, taking $M_{1}>0$ as in (iii) of Lemma 3.4, the functional $\mathcal{J}_{1}$ satisfies the $(w C P S)_{\beta}$ condition for any $\beta>M_{1}$.
Proof. Let $\beta>M_{1}$ and $\left(u_{n}\right)_{n}$ be a $(C P S)_{\beta}$-sequence of $\mathcal{J}_{1}$ in $X$. Then, for $n$ large enough it is

$$
\mathcal{J}_{1}\left(u_{n}\right) \geq M_{1} \quad \text { and } \quad\left|\left\langle d \mathcal{J}_{1}\left(u_{n}\right), u_{n}\right\rangle\right| \leq\left\|d \mathcal{J}_{1}\left(u_{n}\right)\right\|_{X^{\prime}}\left(\left\|u_{n}\right\|_{X}+1\right) \leq \frac{1}{2}
$$

hence, from (iii) of Lemma 3.4 we obtain

$$
\mathcal{J}_{1}\left(u_{n}\right)=\mathcal{J}\left(u_{n}\right), \quad d \mathcal{J}_{1}\left(u_{n}\right)=d \mathcal{J}\left(u_{n}\right),
$$

which implies that $\left(u_{n}\right)_{n}$ is a $(C P S)_{\beta}$-sequence of $\mathcal{J}$ in $X$, too. Thus, from Proposition 4.5 it follows that $u \in X$ exists such that $\left\|u_{n}-u\right\|_{H} \rightarrow 0$ (up to subsequences) and $u$ is a critical point of $\mathcal{J}$ at level $\beta$. Then, $u$ is a critical point of $\mathcal{J}_{1}$ at level $\beta$, too (see Remark 3.5).

## 5. PROOF OF THE MAIN THEOREM

Throughout this section, assume that $A(x, t, \xi), g(x, t), h(x)$ satisfy all the hypotheses of Theorem 2.6.

In order to introduce a suitable decomposition of $X$, let $\left(\lambda_{j}\right)_{j}$ be the sequence of the eigenvalues of $-\Delta$ in $H_{0}^{1}(\Omega)$ and for each $j \in \mathbb{N}$ let $\varphi_{j} \in H_{0}^{1}(\Omega)$ be the eigenfunction corresponding to $\lambda_{j}$.

We recall that $0<\lambda_{1}<\lambda_{2} \leq \lambda_{3} \leq \ldots$, with $\lambda_{j} \nearrow+\infty$ as $j \rightarrow+\infty$, and $\left(\varphi_{j}\right)_{j}$ is an orthonormal basis of $H_{0}^{1}(\Omega)$ such that for each $j \in \mathbb{N}$ it is $\varphi_{j} \in L^{\infty}(\Omega)$; hence, $\varphi_{j} \in X$ (see [6, Section 9.8]). Then, for any $k \in \mathbb{N}$, it is

$$
H_{0}^{1}(\Omega)=V_{k} \oplus Z_{k},
$$

where

$$
V_{k}=\operatorname{span}\left\{\varphi_{1}, \ldots, \varphi_{k}\right\} \quad \text { and } \quad Z_{k} \text { is its orthogonal complement. }
$$

Thus, setting $Z_{k}^{X}=Z_{k} \cap L^{\infty}(\Omega)$, we have

$$
X=V_{k}+Z_{k}^{X} \quad \text { and } \quad V_{k} \cap Z_{k}^{X}=\{0\} ;
$$

whence,

$$
\begin{equation*}
\operatorname{codim} Z_{k}^{X}=\operatorname{dim} V_{k}=k \tag{5.1}
\end{equation*}
$$

Proposition 5.1. If $V$ is a finite dimensional subspace of $X$, then

$$
\sup _{u \in S_{R}^{H} \cap V} \mathcal{J}_{1}(u) \rightarrow-\infty \quad \text { if } R \rightarrow+\infty \text {, }
$$

with $S_{R}^{H}=\left\{u \in X:\|u\|_{H}=R\right\}$.

Proof. Since in a finite dimensional space all the norms are equivalent, the proof follows from definition (3.4) and the estimates (2.10), (2.12), (2.15), (3.7).

From (5.1) and Proposition 5.1 a strictly increasing sequence of positive numbers $\left(R_{k}\right)_{k}$ exists, $R_{k} \nearrow+\infty$, such that for any $k \in \mathbb{N}$ we have that

$$
\mathcal{J}_{1}(u)<0 \quad \text { for all } u \in V_{k} \text { with }\|u\|_{H} \geq R_{k}
$$

Now, we can introduce the following notations:

$$
\begin{aligned}
\Gamma_{k} & =\left\{\gamma \in C\left(V_{k}, X\right): \gamma \text { is odd, } \gamma(u)=u \text { if }\|u\|_{H} \geq R_{k}\right\}, \\
\Gamma_{k}^{H} & =\left\{\gamma \in C\left(V_{k}, H_{0}^{1}(\Omega)\right): \gamma \text { is odd, } \gamma(u)=u \text { if }\|u\|_{H} \geq R_{k}\right\}, \\
\Lambda_{k} & =\left\{\gamma \in C\left(V_{k+1}^{+}, X\right):\left.\gamma\right|_{V_{k}} \in \Gamma_{k} \text { and } \gamma(u)=u \text { if }\|u\|_{H} \geq R_{k+1}\right\},
\end{aligned}
$$

with

$$
V_{k+1}^{+}=\left\{v+t \varphi_{k+1} \in X: v \in V_{k}, t \geq 0\right\}
$$

and

$$
b_{k}=\inf _{\gamma \in \Gamma_{k}} \sup _{u \in V_{k}} \mathcal{J}_{1}(\gamma(u)), \quad b_{k}^{+}=\inf _{\gamma \in \Lambda_{k}} \sup _{u \in V_{k+1}^{+}} \mathcal{J}_{1}(\gamma(u)) .
$$

The following existence result can be proved.
Proposition 5.2. Assume $q<2^{*}(s+1)$ and let $k \in \mathbb{N}$ be such that

$$
\begin{equation*}
b_{k}^{+}>b_{k} \geq M_{1}, \tag{5.2}
\end{equation*}
$$

with $M_{1}>0$ as in (iii) of Lemma 3.4. Taking $0<\delta<b_{k}^{+}-b_{k}$, define

$$
\beta_{k}(\delta)=\inf _{\gamma \in \Lambda_{k}(\delta)} \sup _{u \in V_{k+1}^{+}} \mathcal{J}_{1}(\gamma(u))
$$

where

$$
\Lambda_{k}(\delta)=\left\{\gamma \in \Lambda_{k}: \mathcal{J}_{1}(\gamma(u)) \leq b_{k}+\delta \text { if } u \in V_{k}\right\}
$$

Then, $\beta_{k}(\delta)$ is a critical level of $\mathcal{J}$ in $X$ with $\beta_{k}(\delta) \geq b_{k}^{+}$.
Proof. The proof follows from Proposition 4.6 by reasoning as in [16, Proposition 5.4].

Now, we need an estimate from below for the sequence $\left(b_{k}\right)_{k}$.
Proposition 5.3. If $q<2^{*}(s+1)$, then a constant $C_{1}>0$ exists such that

$$
b_{k} \geq C_{1} k^{\frac{2 q}{N(q-2-2 s)}} \quad \text { for } k \text { large enough. }
$$

Proof. Firstly, we note that from (2.1), (2.5), (2.15), (3.4), (3.7) and direct computations, some constants $a_{10}, a_{11}, a_{12}>0$ exist, such that

$$
\begin{equation*}
\mathcal{J}_{1}(u) \geq a_{10} \mathcal{I}(u)-a_{11} \quad \text { for all } u \in X, \tag{5.3}
\end{equation*}
$$

where $\mathcal{I}: X \rightarrow \mathbb{R}$ is the $C^{1}$ functional defined as

$$
\mathcal{I}(u)=\frac{1}{2} \int_{\Omega}\left(1+|u|^{2 s}\right)|\nabla u|^{2} d x-a_{12} \int_{\Omega}|u|^{q} d x
$$

Now, taking $k \in \mathbb{N}$, reasoning as in the proof of [16, Proposition 5.6], for any $\gamma_{0} \in \Gamma_{k}$ we can define the continuous map $\tilde{\gamma}_{0}: V_{k} \rightarrow X$,

$$
\tilde{\gamma}_{0}(u)= \begin{cases}\left|\gamma_{0}(u)\right|^{s} \gamma_{0}(u) & \text { if }\|u\|_{H} \leq R_{k}-\delta_{0} \\ \left|\gamma_{0}(u)\right|^{\frac{s}{\delta_{0}}}\left(R_{k}-\|u\|_{H}\right) \\ u & \gamma_{0}(u) \\ \text { if } R_{k}-\delta_{0}<\|u\|_{H}<R_{k}, \\ \text { if }\|u\|_{H} \geq R_{k},\end{cases}
$$

for a suitable $\left.\delta_{0} \in\right] 0, R_{k}\left[\right.$, such that $\tilde{\gamma}_{0} \in \Gamma_{k} \subset \Gamma_{k}^{H}$ and

$$
\sup _{u \in V_{k}} \mathcal{I}\left(\gamma_{0}(u)\right) \geq \frac{1}{(s+1)^{2}} \sup _{u \in V_{k}} K^{*}\left(\tilde{\gamma}_{0}(u)\right) \geq \frac{1}{(s+1)^{2}} \inf _{\gamma \in \Gamma_{k}^{H}} \sup _{u \in V_{k}} K^{*}(\gamma(u))
$$

with

$$
K^{*}(v)=\frac{1}{2} \int_{\Omega}|\nabla v|^{2} d x-a_{12}(s+1)^{2} \int_{\Omega}|v|^{\frac{q}{s+1}} d x
$$

Then, the thesis follows from [26, Section 2] and (5.3).
Proof of Theorem 2.6. Since $b_{k}^{+} \geq b_{k}$ for any $k \in \mathbb{N}$ and $b_{k} \rightarrow+\infty$ from Proposition 5.3, the thesis follows from Proposition 5.2 once we prove that (5.2) holds for infinitely many $k$.

Arguing by contradiction, assume that $k_{1} \in \mathbb{N}$ exists such that $b_{k}^{+}=b_{k}$ for any $k \geq k_{1}$. From Lemma 3.3 and reasoning as in the proof of [23, Proposition 10.46], a constant $C_{2}=C_{2}\left(k_{1}\right)>0$ exists such that

$$
b_{k} \leq C_{2} k^{\frac{\mu}{\mu-1}} \quad \text { for any } k \text { large enough, }
$$

which yields a contradiction from assumption (2.14) and Proposition 5.3.

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